AMENDMENTS TO THE SPECIFICATION

Please replace the paragraph on Page 6, line 7, beginning with "The base plate..." with the following paragraph:

---The base plate 1 further comprises three holes 6 for receiving third 11, fourth 12~~13~~, and fifth 13~~12~~ conductive legs mounted on substrate 10. These legs 11,12,13 form the termination of the 3-pin potentiometer part of the assembly. One of conductive legs 11 or 12 may be omitted, if preferred, thus leaving the potentiometer part in a 2-pin version providing an adjustable resistance value between the two legs 11,13 or 12,13.---

Please replace the paragraph on Page 6, line 33, beginning with "The intermediate link..." with the following paragraph:

---The intermediate link 20 has the slidable contact 22 rigidly mounted to its lower side. In a well-known manner the conductive legs 11, 12, 13, the conductive path 14, and the slidable contact ~~22~~ are capable of constituting a conventional voltage divider where the rotation of the conductive wiper 22 provides two mutually dependent variable resistance values between the third conductive leg 11 and the fifth conductive leg 13, and between the fourth conductive leg 12 and the fifth conductive leg 13, respectively.---

Please replace the paragraph on Page 8, line 13, beginning with "Fig. 2 shows..." with the following new paragraph:

---Fig. 2 shows a different perspective view of selected parts of the assembly according to the invention. Bottom part of the rotatable member 40 comprises an opening [44] adapted to fit to a top of the intermediate link 20. The rotatable member 40 also comprises a protrusion 39 adapted to engage with the second part 38 of the resilient tactile member 35 upon rotation of the rotatable member 40. It is apparent that an angular position of the tactile engagement relative to an angular position of the top member 40 where a change

of switch state occurs can be chosen with a high degree of freedom. Thus, a timing experienced by the user between change of switch state and tactile feedback upon rotation of the rotatable member 40 can be varied. This timing corresponds to an angular difference of the rotatable member 40 between the point of engagement of the protrusion 39 and the second part 38 of the resilient tactile member 35 versus the point of engagement of the protrusion 21 of the intermediate link 20 with the second part 9b of the resilient conductive member 8.---